

Estimating uncertainty with the ECMWF ensembles

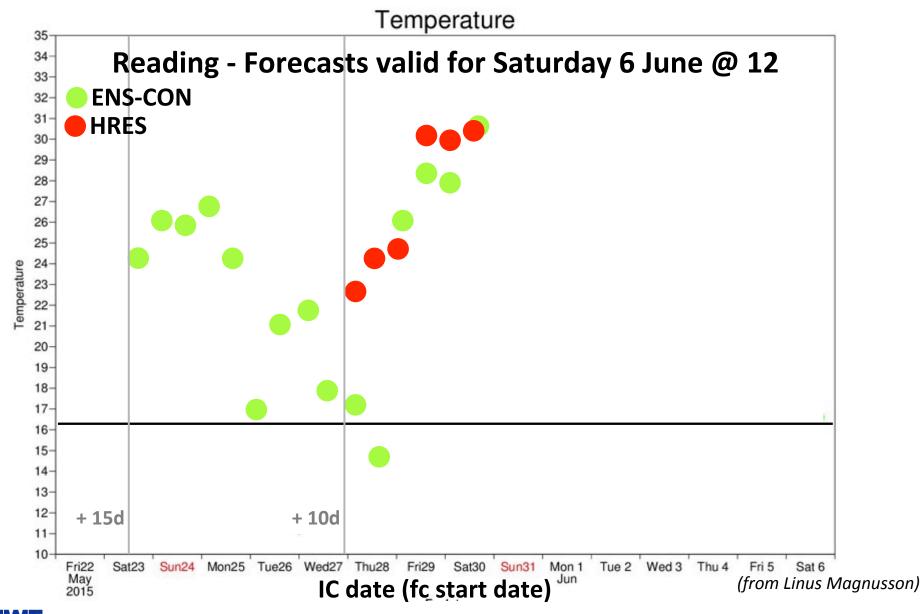
Roberto Buizza

European Centre for Medium-Range Weather Forecasts



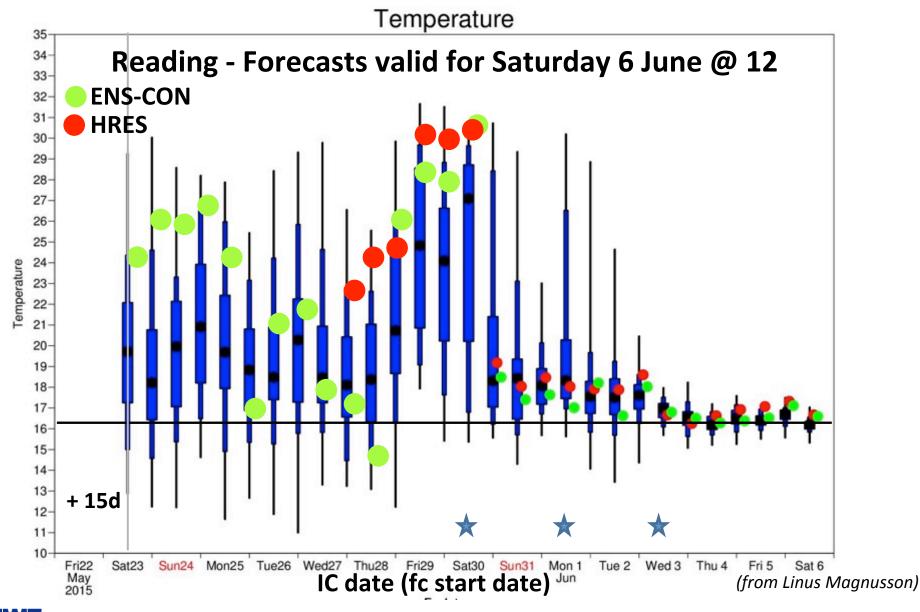
- 1. Why do we need ensembles?
- 2. The ECMWF ensembles
- 3. The resolution upgrade of March 2016
- 4. Few key performance indices
- 5. Prediction of an extreme precipitation event in Houston
- 6. Conclusions

1. Why do we need ensembles?

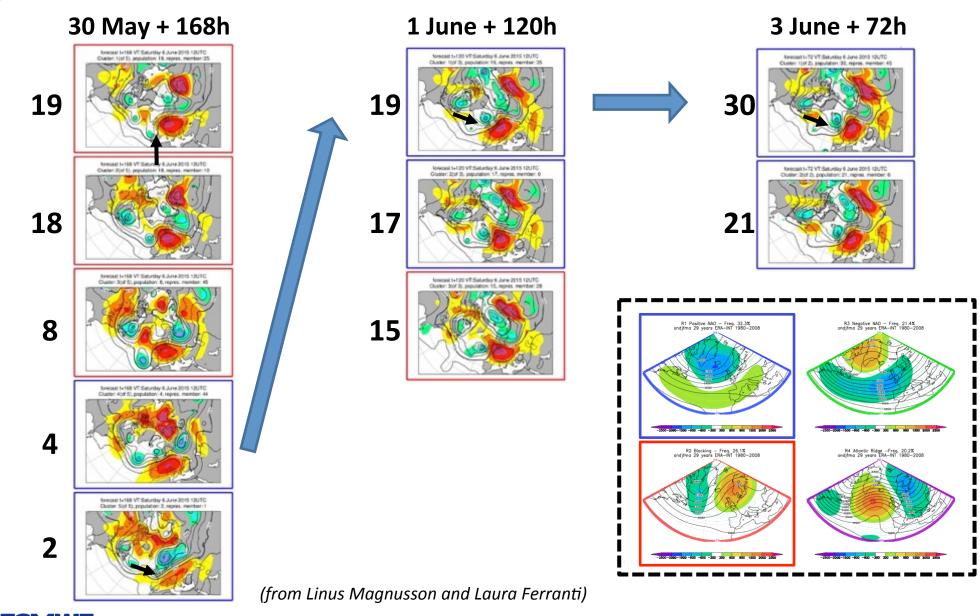


LaMMA (Firenze, 7 July 2016) - Roberto Buizza: Estimating uncertainty with the ECMWF ensembles

1. Why do we need ensembles?



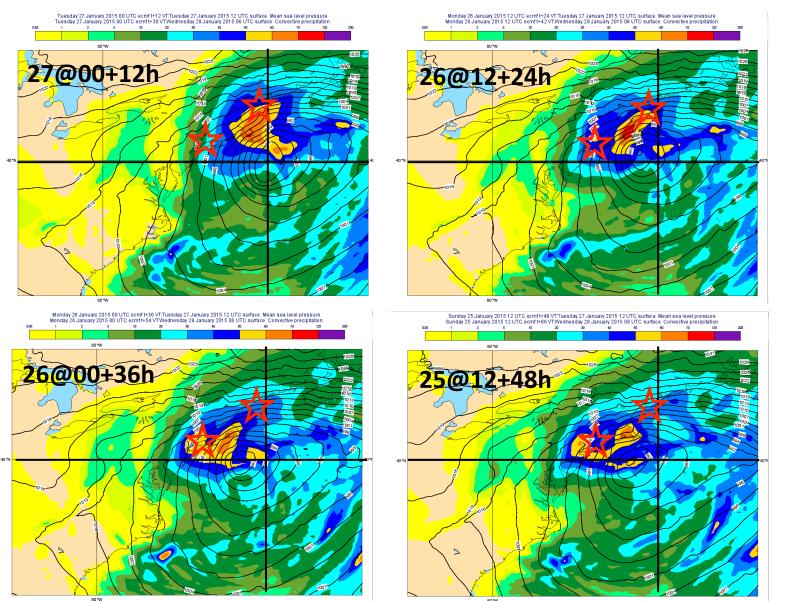
1. Why do we need ensembles?



1. We need ENS even in the short range (US Storm)

Single HRES fcs failed to positioned correctly the storm, and this led to snowfall overestimation for NY of in the 24-36-48h forecasts.

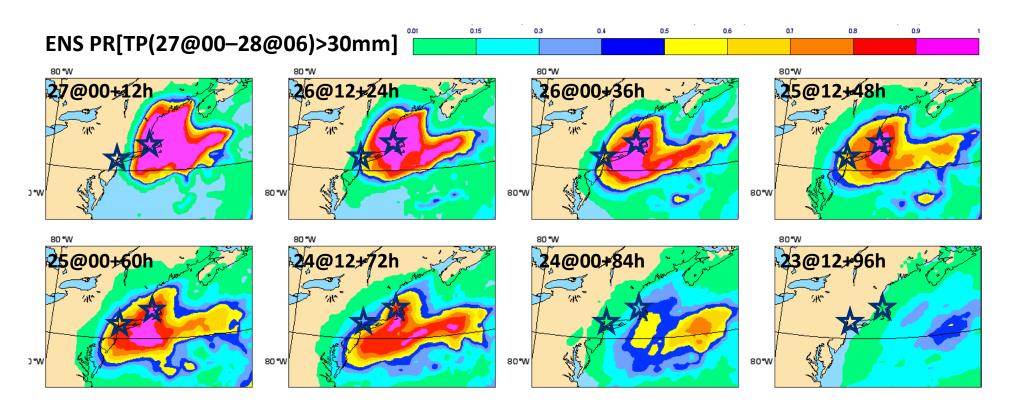
MLSP+TP maps show a 150-200 km eastward shift in the storm centre.





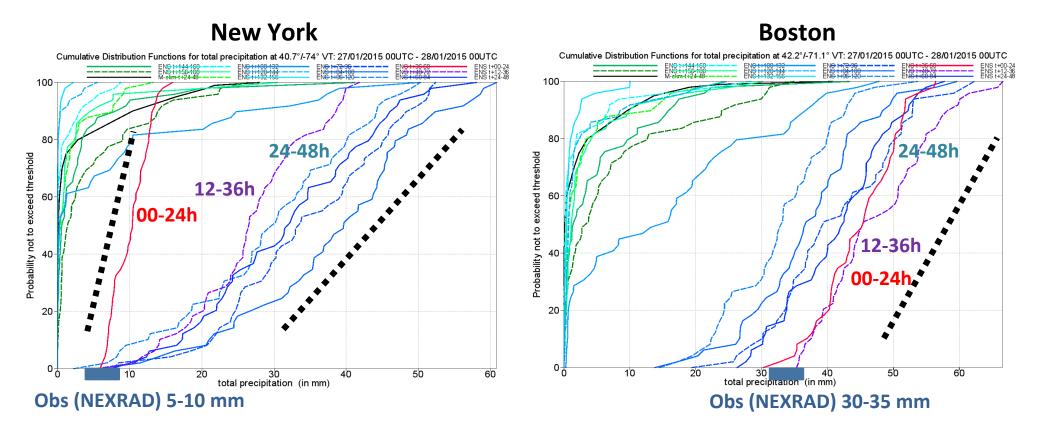
1. US Storm, 27-28/01/2015: ENS PR fcs

ENS-based probabilistic forecasts can be used to estimate the level of confidence (predictability) of single forecasts. They show that NY was closer to the edge of the area of high probability of +30mm of precipitation, indicating higher uncertainty.



1. US Storm, 27-28/01/2015: forecast confidence

ENS-based probabilistic forecasts expressed in terms of CDF shows that the fcs for NY were more uncertain (the slope of the CDF curves is steeper) than the fcs for Boston.



1. A necessary property for ENS to be valuable: reliability

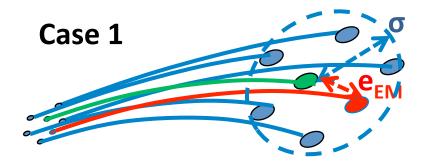
eEM

A reliable ensemble has, on average over many cases M, spread measured by the ensemble standard deviation σ , equal to the average error of the ensemble mean e_{EM} : $\langle \sigma \rangle_{M} = \langle e_{EM} \rangle_{M}$

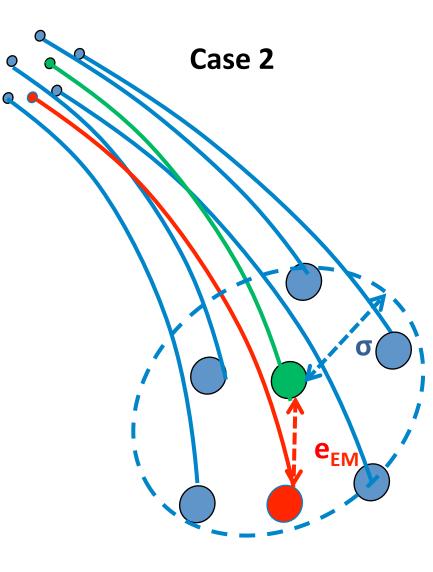
 M_1

 M_2

1. In a reliable ENS, small spread >> high predictability



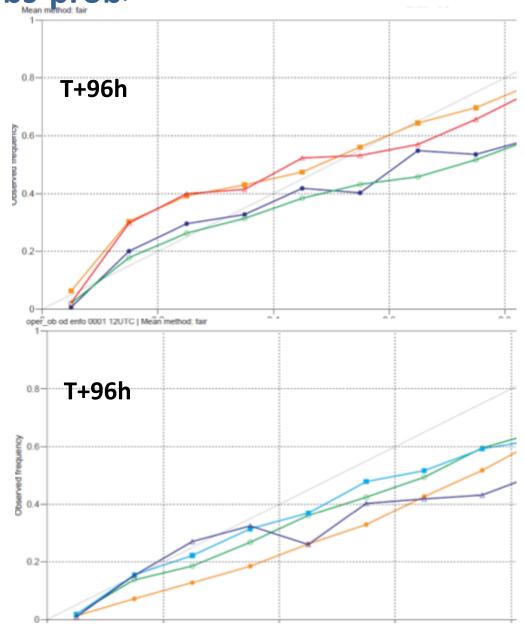
In a reliable ensemble, small ensemble standard deviation indicates a more predictable case, i.e. a small error of the ensemble mean e_{EM} .



1. Reliability: <fc-prob>~<obs-prob>

One way to check the ensemble reliability is to assess whether the average forecast and observed probabilities of a certain event are similar.

These plots compare the two probabilities at t+144h for the event '24h precipitation in excess of 1/5/10/20 mm' (top) and '2mT gt/lt 4/8 degrees' over Europe for MAM16 (verified against observations).



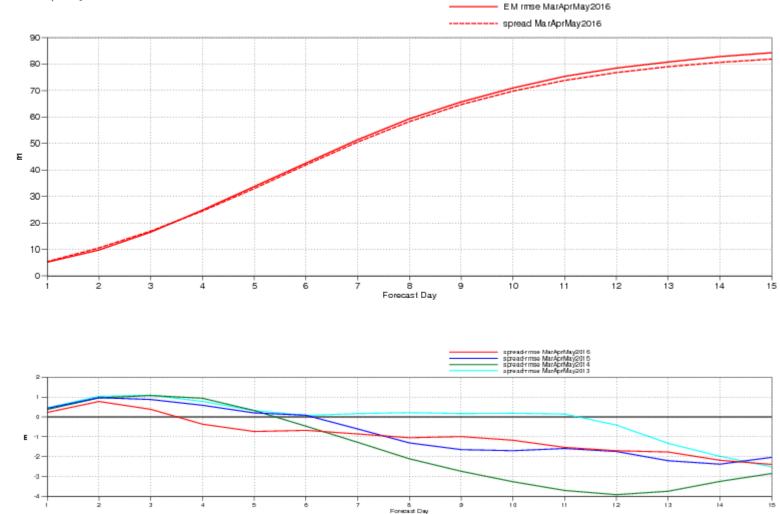
1. ENS reliability: Z500 over NH (MAM16)

ENS Mean RMSE and ENS Spread

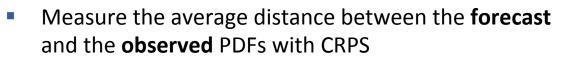
500hPa geopotential NHem Extratropics (lat 20.01090.0, lon -180.0 to 180.0) MarAprMay

In a reliable ensemble the average spread matches the average error of the ensemble mean.

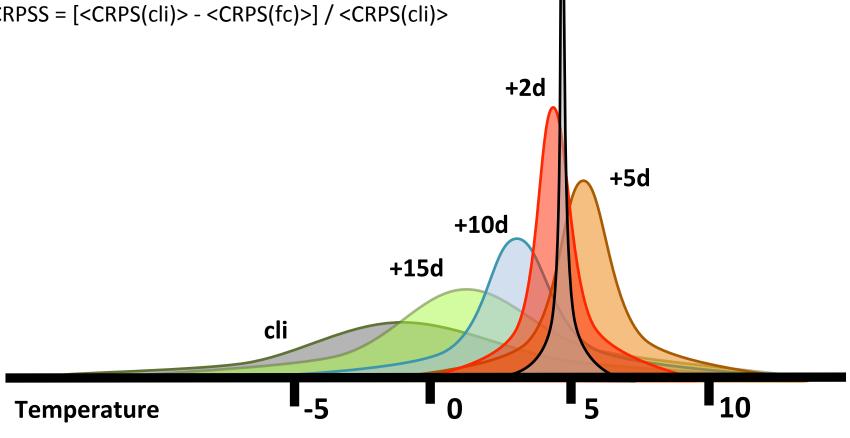
This plot shows the two curves for Z500 over NH in FMA16.



1. PDF forecast skill: how do we measure it?

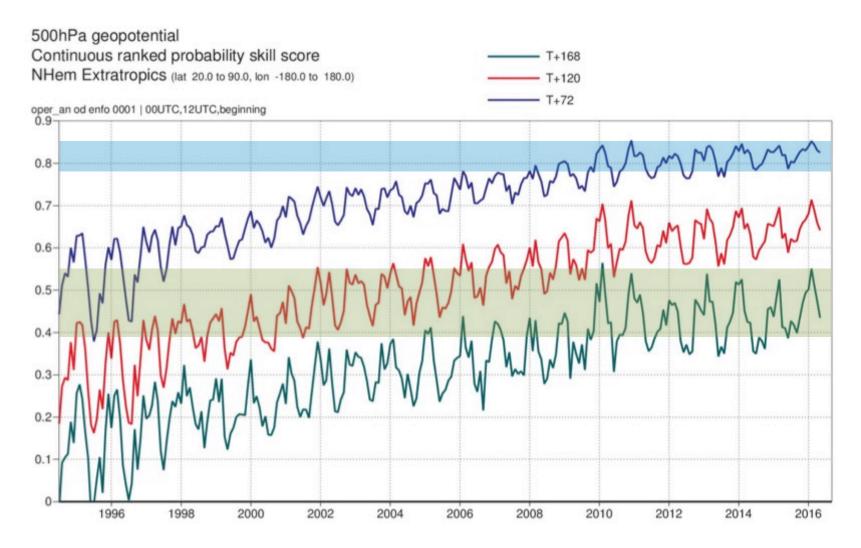


- Measure the average distance between the climatological and the observed PDFs with CRPS
- CRPSS = [<CRPS(cli)> <CRPS(fc)>] / <CRPS(cli)>



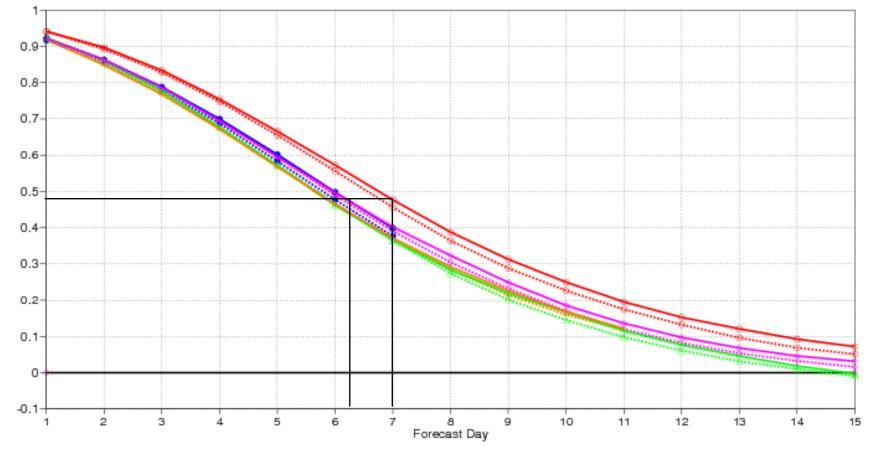


CRPSS is a measure of skill. Today, +7d fcs are as good as +3d fcs 20y ago!



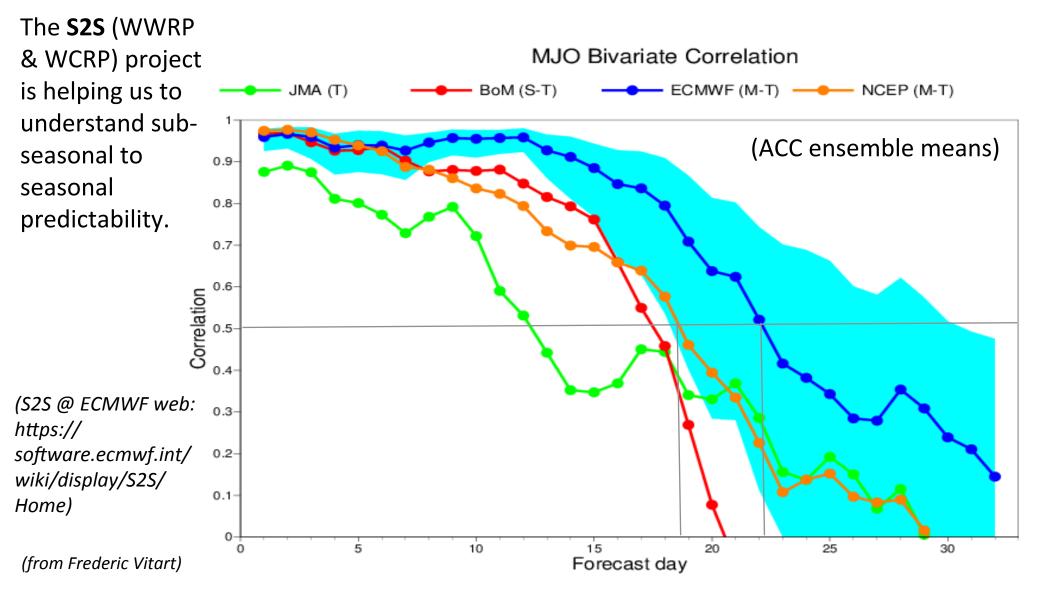
1. The TIGGE ensembles: Z500 over NH, MAM16





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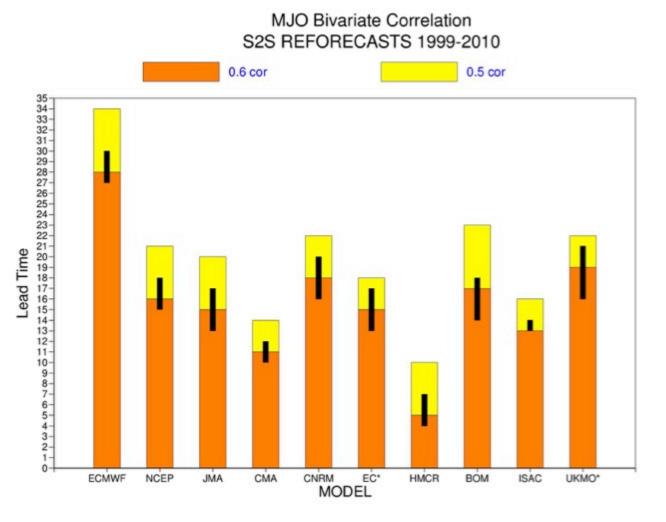


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Forecast lead-time when the ACC for the prediction of the Madden-Julian-Oscillation (MJO) reaches 0.6 correlation (orange bars) and 0.5 correlation (yellow bars). The black lines indicate the 95% confidence interval of the time when the 0.6 correlation is reached.

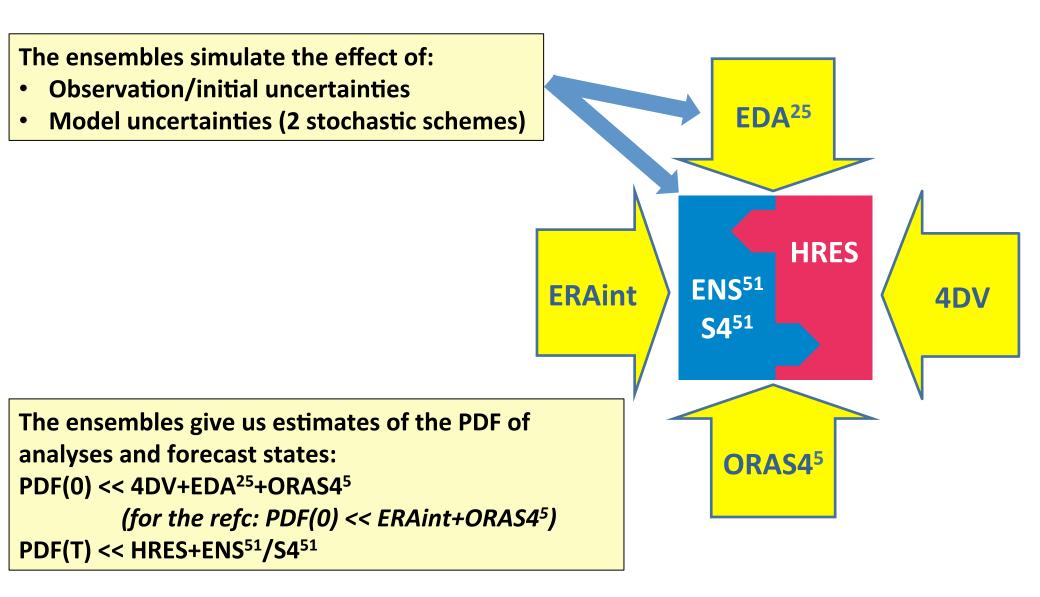
Results are based on the reforecast from 1999 to 2010 from all the models, verified against ERA-Interim analyses.





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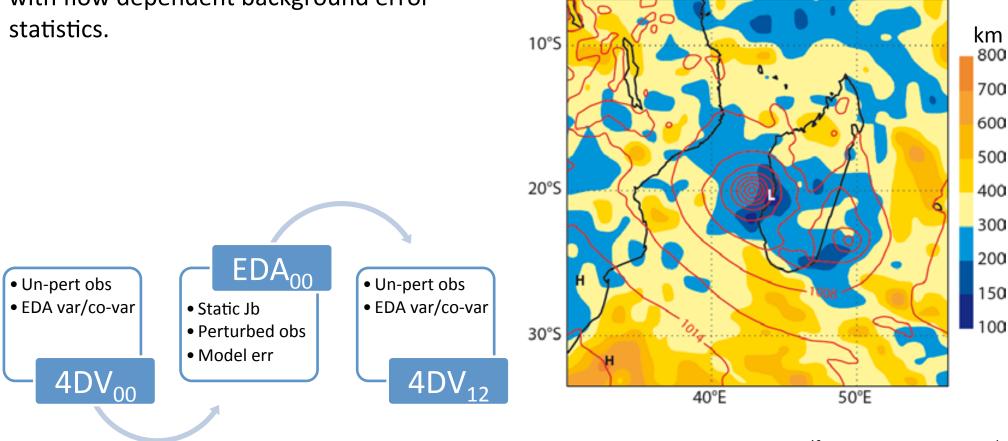
2. Ensembles are used at analysis and forecast time



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2. The EDA is used to provide flow dependent stats

The 25-member **Ensemble of Data Assimilations** provides the 4DV-HRES with flow dependent background error statistics. Background error correlation length scale for long(p_{msl}) and p_{msl}



2. The medium-range/monthly ensemble (ENS)

ENS includes **51 forecasts** with resolution:

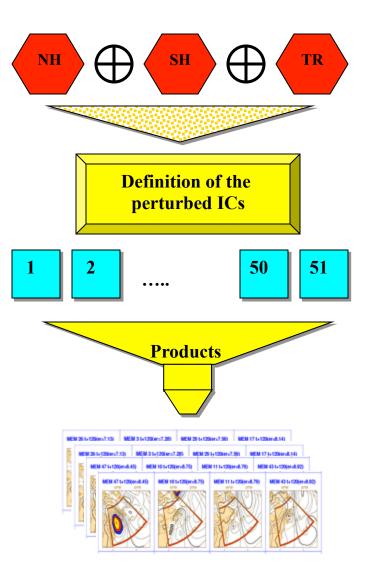
- T_{co}639L91 (~18km, 91 levels) from day 0 to 15
- T_{co}319L91 (**~36km**, 91 levels) from **day 15 to 46** (only at 00UTC on Mon and Thu).

Initial uncertainties are simulated by adding to the unperturbed analyses a combination of **T42L91 singular vectors**, computed to optimize total energy over 48h hours, and perturbations generated by the ECMWF **T**_{co}639L137 EDA (Ensembles of Data Assimilation).

Model uncertainties are simulated by adding stochastic perturbations to the tendencies due to parameterized physical processes (SPPT and SKEB schemes).

The unperturbed analysis is given by the T_{co}1279L137 4DVAR.

ENS runs daily at 00 and 12 UTC, with a TOA at 0.01 hPa.



2. The ECMWF operational ensemble (ENS) today

Each ensemble forecast is given by the time integration of perturbed equations

$$e_{j}(d,T) = e_{j}(d,0) + \int_{0}^{T} [A(e_{j},t) + P(e_{j},t) + \delta P_{j}(e_{j},t)]dt$$

$$\downarrow$$

$$\delta P_{j}(\lambda,\varphi,p) = r_{j}(\lambda,\varphi)P_{j}(\lambda,\varphi,p) + F_{\Psi}(\lambda,\varphi,p)$$
SPPT: Stochastically Perturbed Parameterized Tendencies

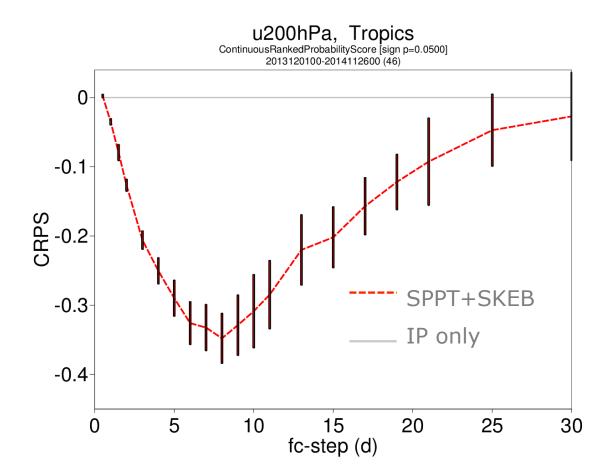
(to represent uncertainty associated with parameterisations)

SKEB: Stochastic Kinetic Energy Backscatter (to represent unresolved upscale energy transfer)

2. Including model uncertainties improves ENS forecasts

Including model perturbations via the SPPT and SKEB schemes gives rise to better ensembles:

- The ensemble is more reliable (less underdispersive);
- Improved probabilistic skill is observed at a range of lead times (e.g. see in plot improved CRPS for high-level winds in the Tropics)





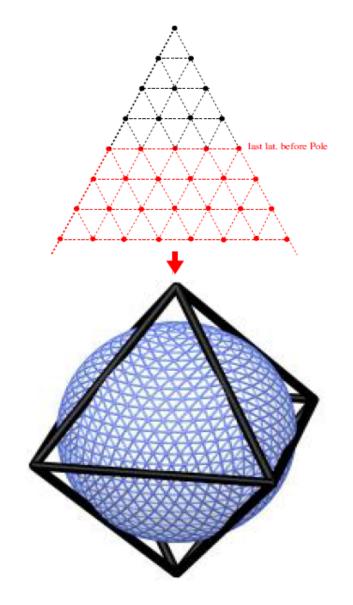
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3. The octahedral cubic grid

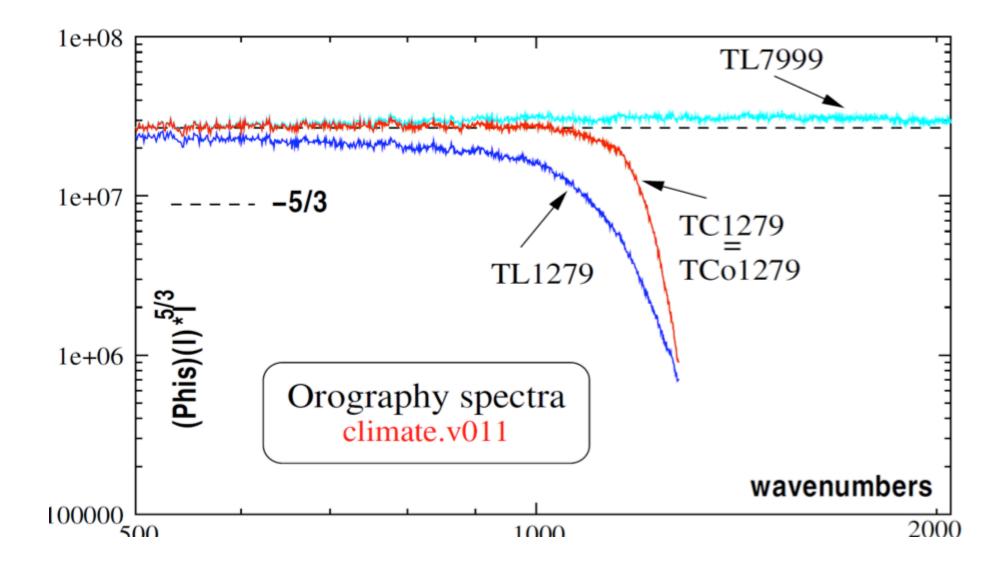
It is a reduced Gaussian grid with the same number of latitude circles (*NDGL*) than the standard Gaussian grid (↔ Gaussian weights) but with a new rule to compute the number of points per latitude circle.

Number of points per latitude NLOEN(lat_N)=20 \rightarrow Poles NLOEN(lat_i)=NLOEN(lat_{i-1})+4

TL1279 :2.14 Mpoints TC1023 :5.45 Mpoints TC1279 :8.51 Mpoints TC01279 :6.59 Mpoints



3. Orographic variance of different grids



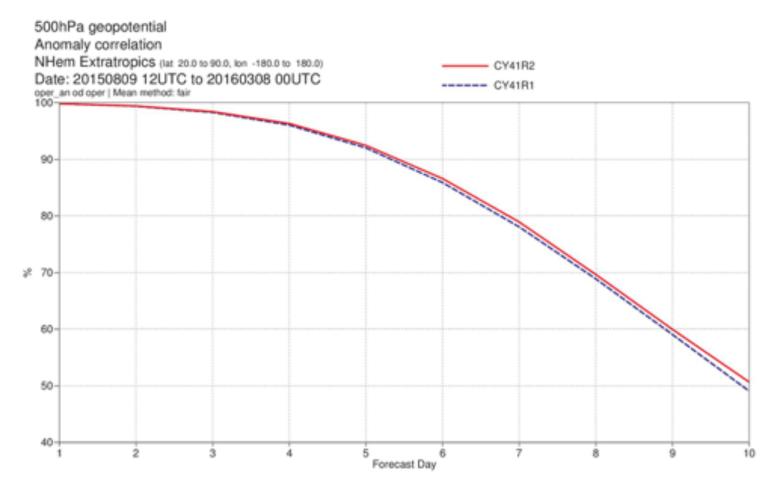
3. March 2016: the resolution of all suites was increased

	Operational suite	Uncertainty sources		
		Obs	ICs	Model
HRES - 9km	T _{co} 1279 (~9 km) L137 (0-10d)			
4DVAR- 9km	T _{co} 1279 (inner T _{co} 255/319/399) L137			
EDA – 18km	25 members: T _{co} 639 (~18km) L137	δο		SPPT(1L)
ENS – 18km	51 members: T _{co} 639 (~18km) L91 (0-15d) T _{co} 319 (~36km) L91 (15-46d) - Ocean: NEMO ORCA100z42 <i>(to 025z75 in Q4)</i>		EDA ²⁵ & SVs ^{50*Nareas} ORAS4 ⁵	SPPT(3L) & SKEB
S4 – 80km	51 members: T _L 255 (~80km) L91 <i>(to T_{cO}319L137 in 2017)</i> - Ocean: NEMO ORCA100z42 <i>(to 025z75 in 2017)</i>		SVs ORAS4 ⁵	SPPT(3L) & SKEB

 T_{CO} – Cubic octahedral Gaussian reduced grid T_{L} – Gaussian linear grid

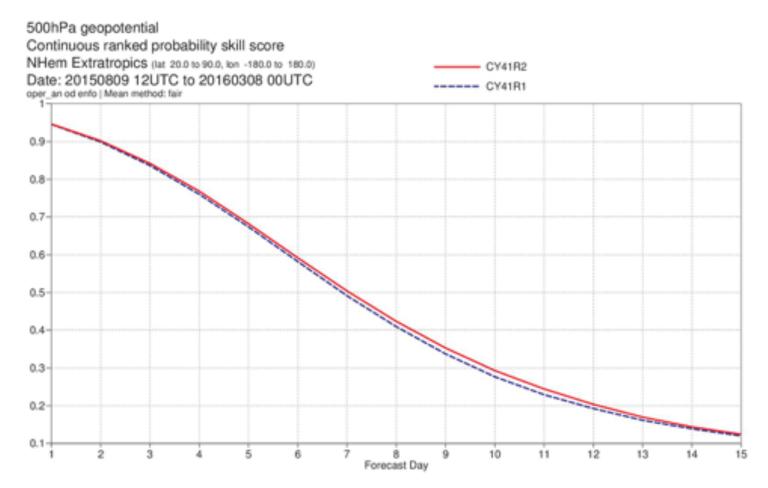
3. Impact of recent upgrade on single high-resolution fc

Results based on 7 months indicate predictability gains for single high-resolution forecasts in the medium-range of **about 3 hours** (up to 6 hours for surface variables).



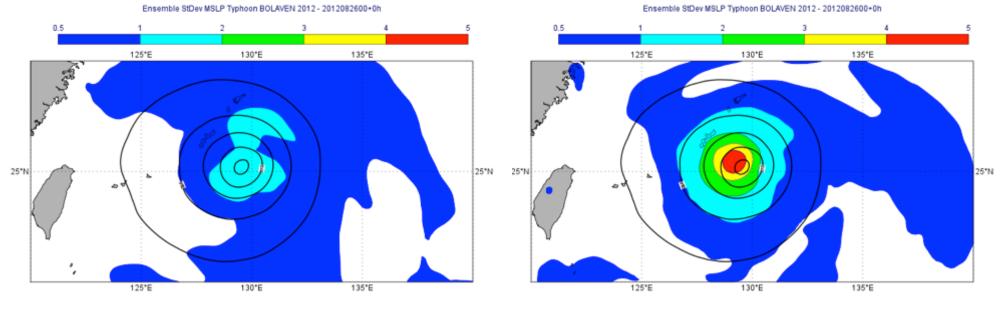
3. Impact of recent upgrade on ensemble fcs

Results based on 7 months indicate predictability gains for the ensemble in the medium-range of **about 6 hours** (up to 12-18 hours for surface variables).



3. Impact of using a higher-resolution EDA

An increase in the resolution of the EDA outer loops from T_L399 to T_L639 improves the estimation of the analysis uncertainty and thus the ENS initial conditions. This figure shows the impact on the ENS spread (std) in the case of typhoon Bolaven (26 Aug 2012).



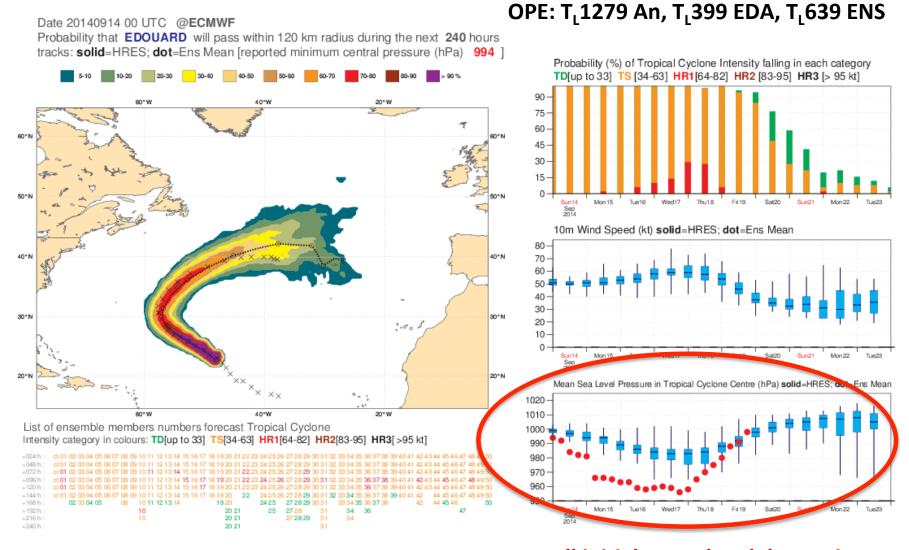
Ensemble with perturbations from 399 EDA

(From Simon Lang)

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Ensemble with perturbations from 639 EDA

3. Combined impact of increasing EDA & ENS resolution

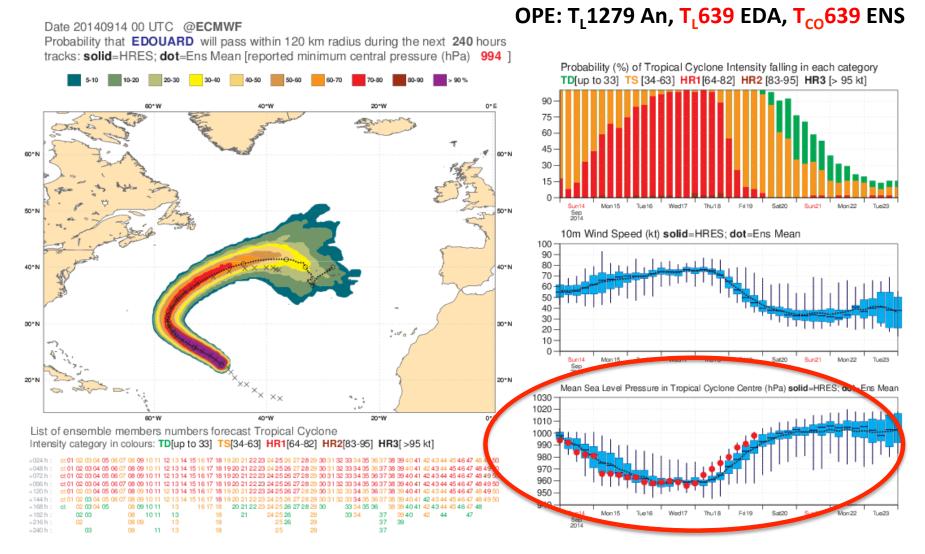


(From Simon Lang)

Too small initial spread and deepening not captured

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3. Combined impact of increasing EDA & ENS resolution



(From Simon Lang)

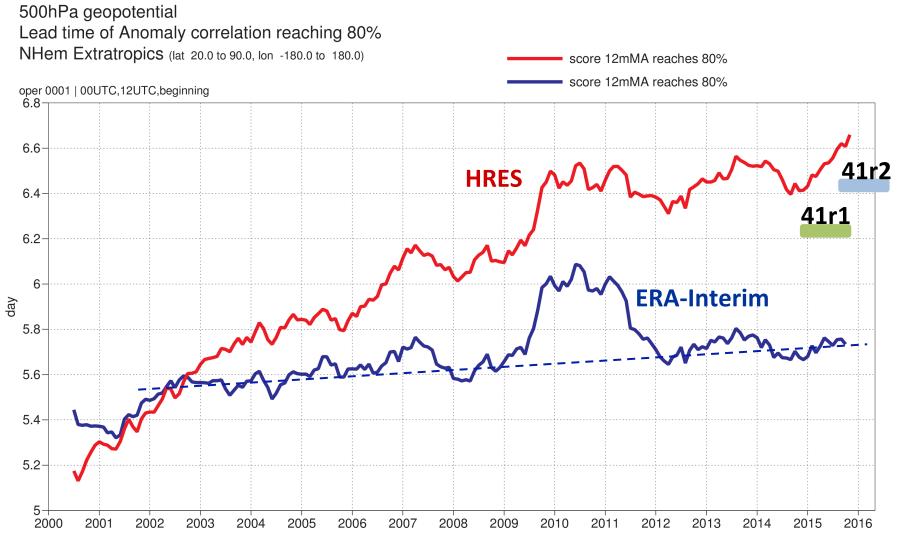
Deepening is captured and spread reflects uncertainty

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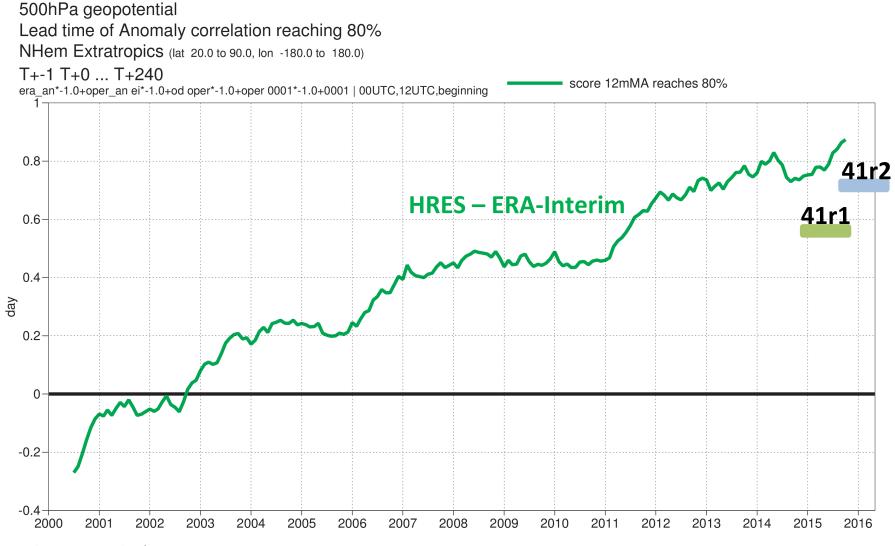
4. HRES and ERAI headline score – Z500 ACC NH



(From Thomas Haiden)

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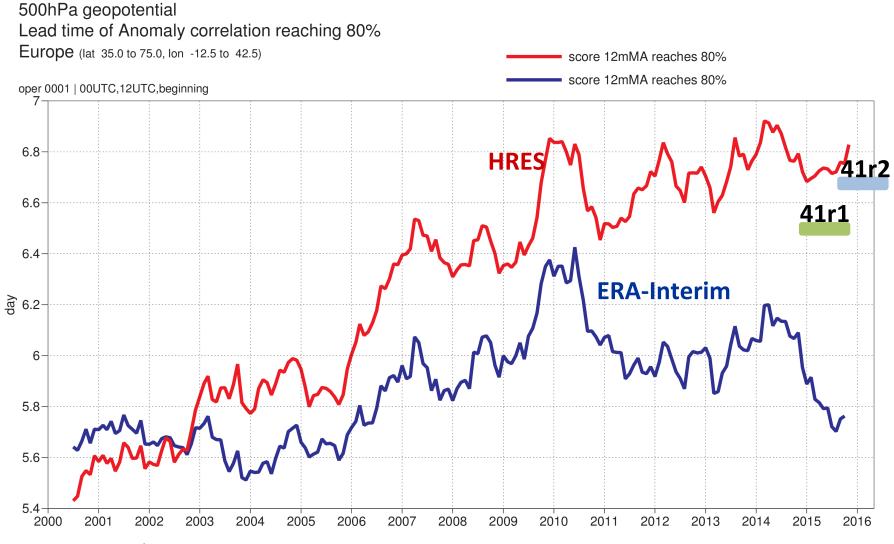
4. (HRES-ERAI) headline score – Z500 ACC NH



(From Thomas Haiden)

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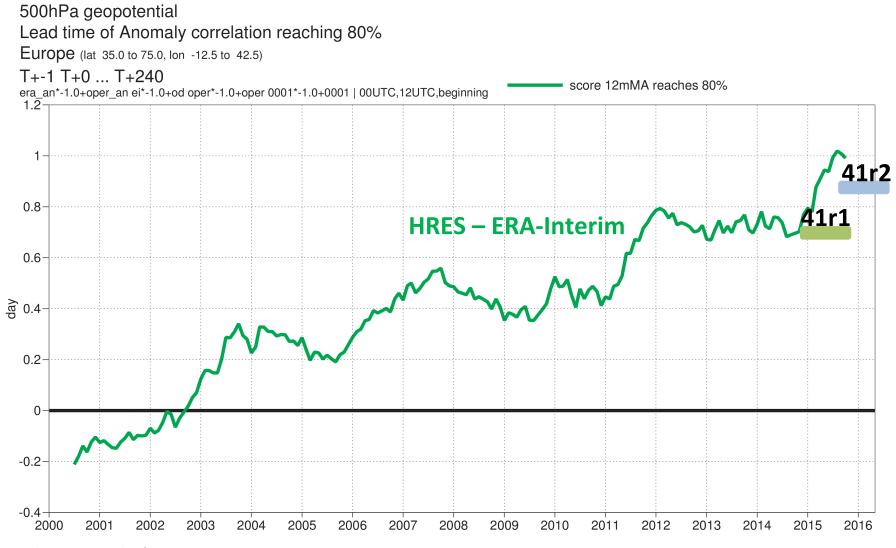
4. HRES and ERAI headline score – Z500 ACC Europe



(From Thomas Haiden)

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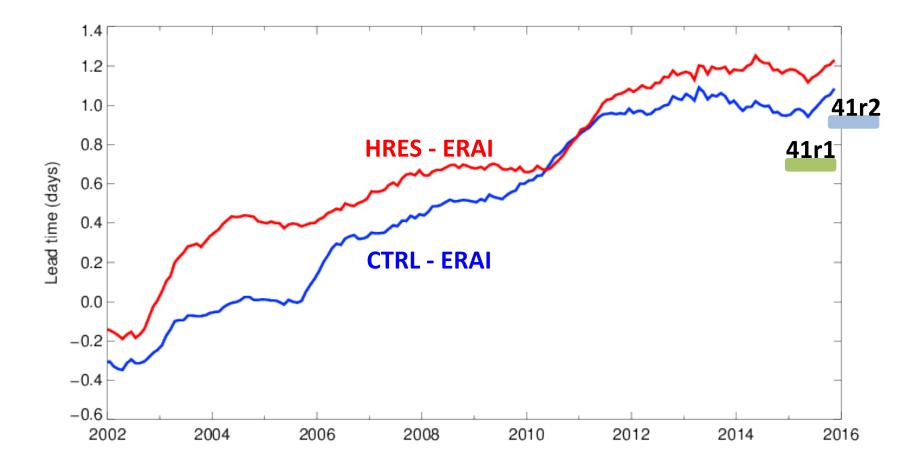
4. (HRES-ERAI) headline score – Z500 ACC Europe



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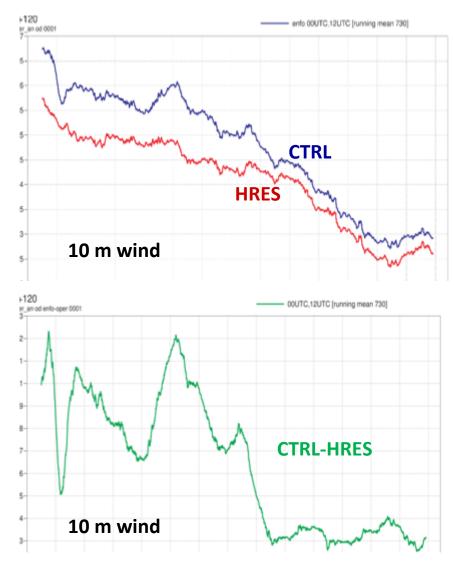


Difference HRES-CTRL: reduced with 41r1, but no strong signal from 41r2 (yet).

(From Thomas Haiden)

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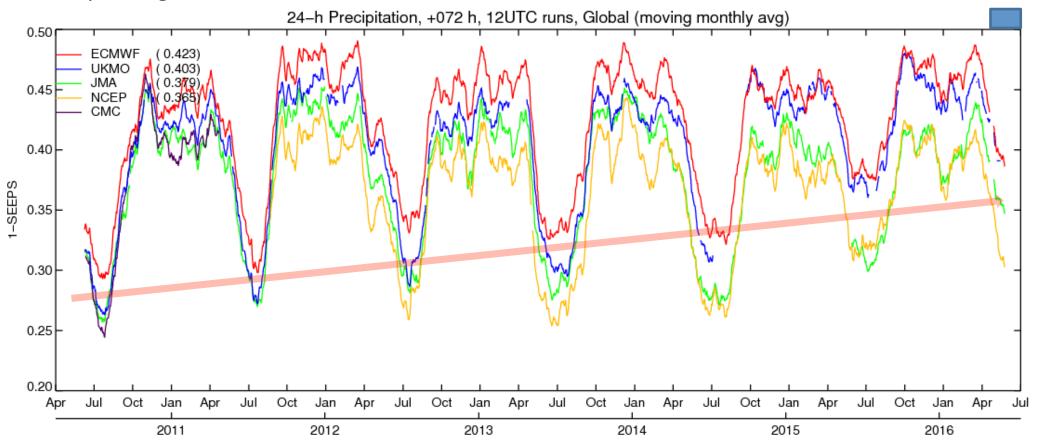


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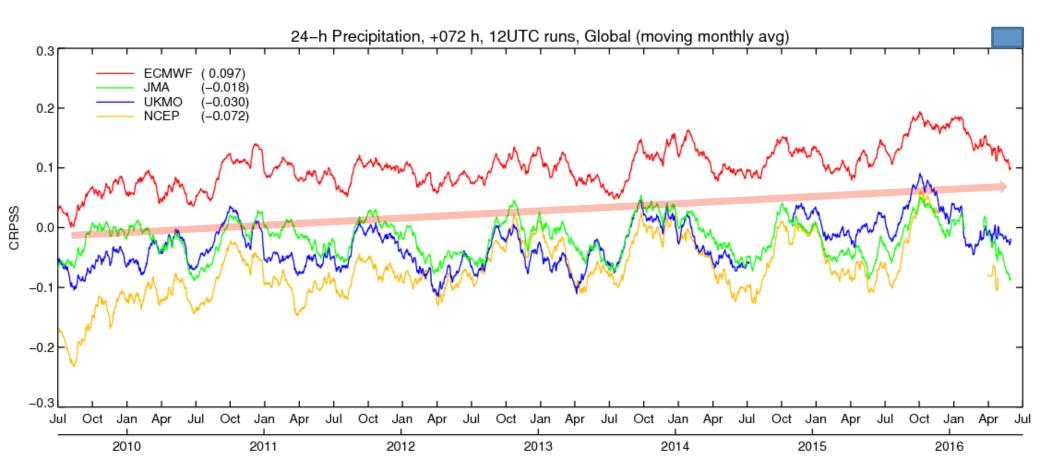
4. High-resolution single precipitation fc: t+72h

The accuracy of single high-resolution 72-h precipitation forecast (verified against observations), measured by the SEEPS score, for ECMWF and UKMO has been slowly improving.



4. Impact of recent upgrade on single high-resolution fc

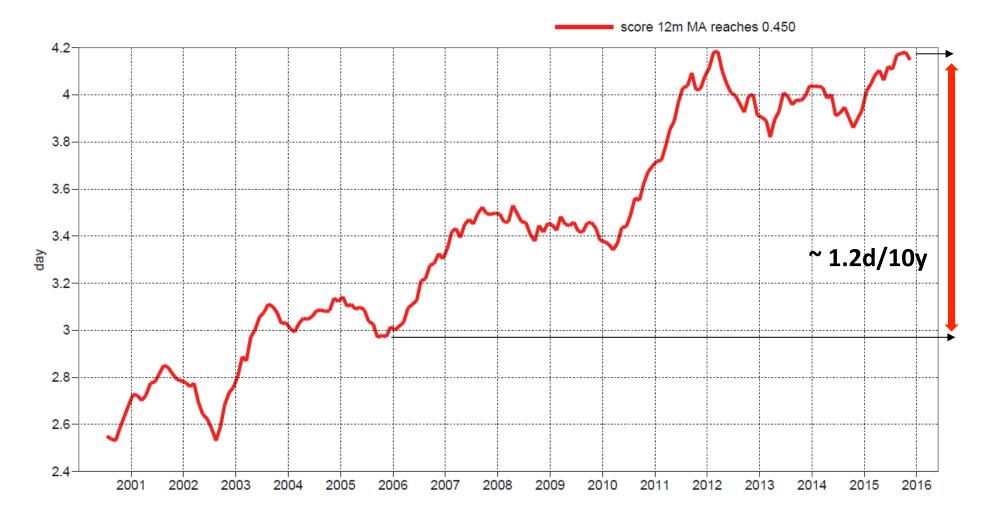
The accuracy of 72-h probabilistic precipitation forecast (verified against observations), measured by the CRPSS, has also been slowly improving.



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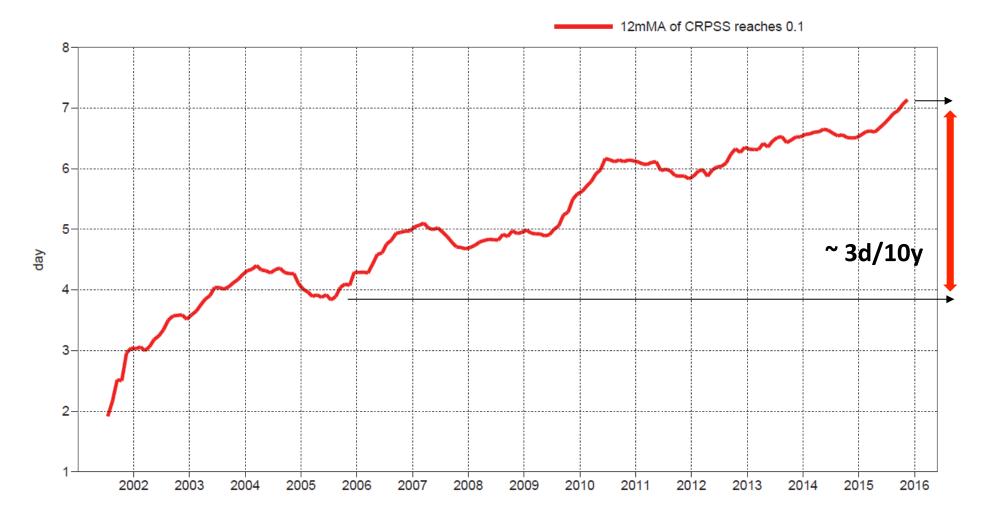
4. ENS CRPSS – 24-h precipitation NH

total precipitation 1-SEEPS Extratropics (lat -90 to -30.0 and 30.0 to 90, lon -180.0 to 180.0)



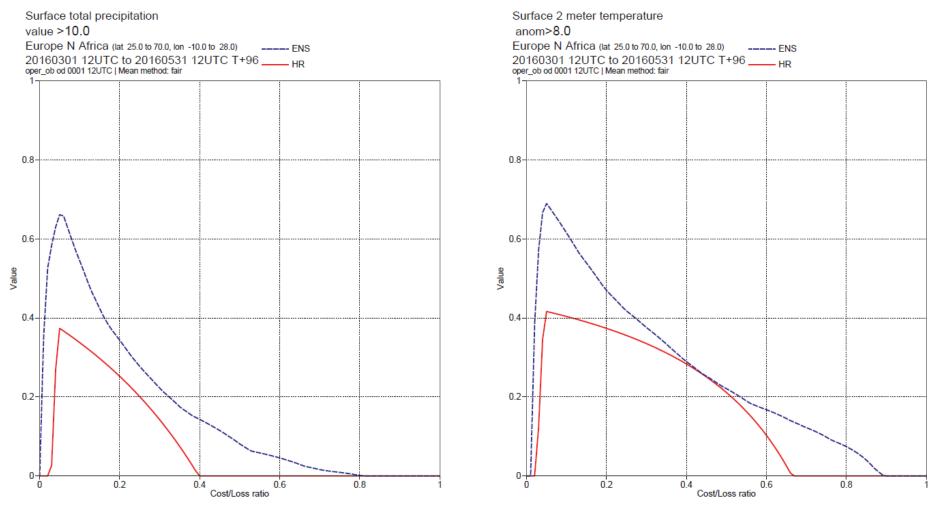
4. ENS CRPSS – 24-h precipitation NH

total precipitation Continuous ranked probability skill score Extratropics (lat -90 to -30.0 and 30.0 to 90, lon -180.0 to 180.0)



4. The Potential Economic Value: a cost-loss based metric

A cost-loss model can be used to assess the Potential Economic Value of single and probabilistic forecasts. Results indicate that these latter are more valuable.





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6. Houston, Texas – April 2016: 16@12 to 19@12



(From Ervin Tsoter)

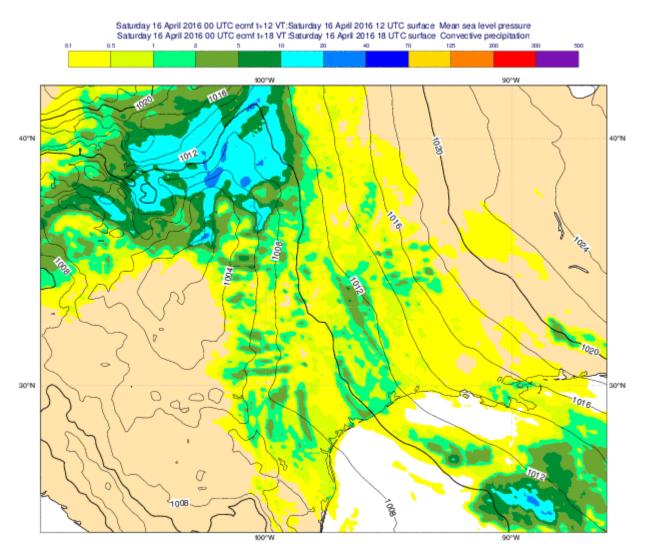
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04/19/2016 13:00 UTC

River Forecast Center Boundaries

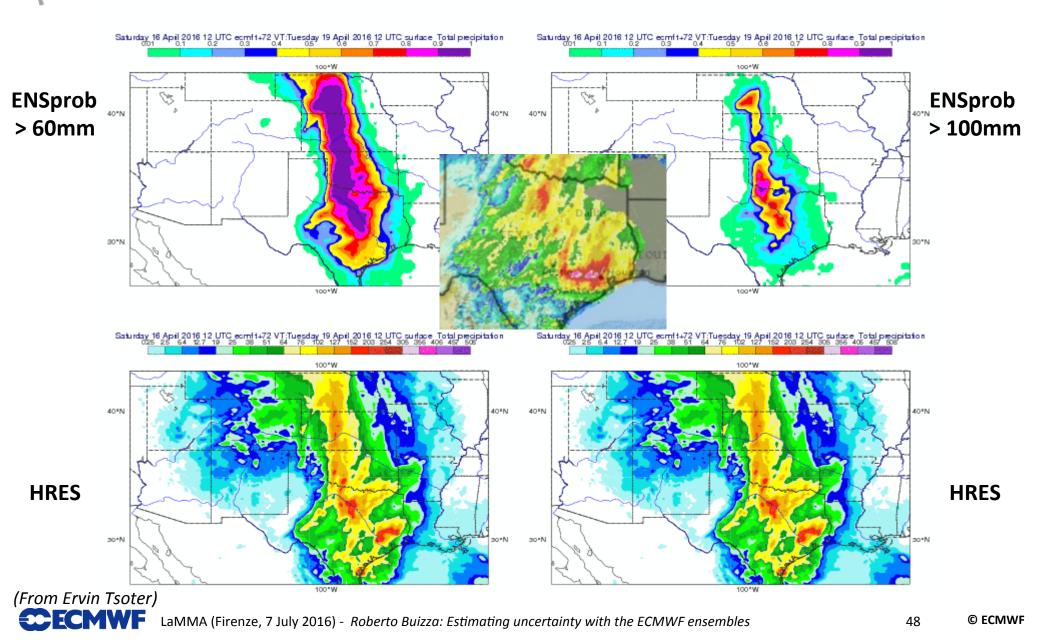
6. Houston, Texas, 16-19 April 2016

A very slow moving system bringing a continuous supply of warm and moist air from the Gulf.

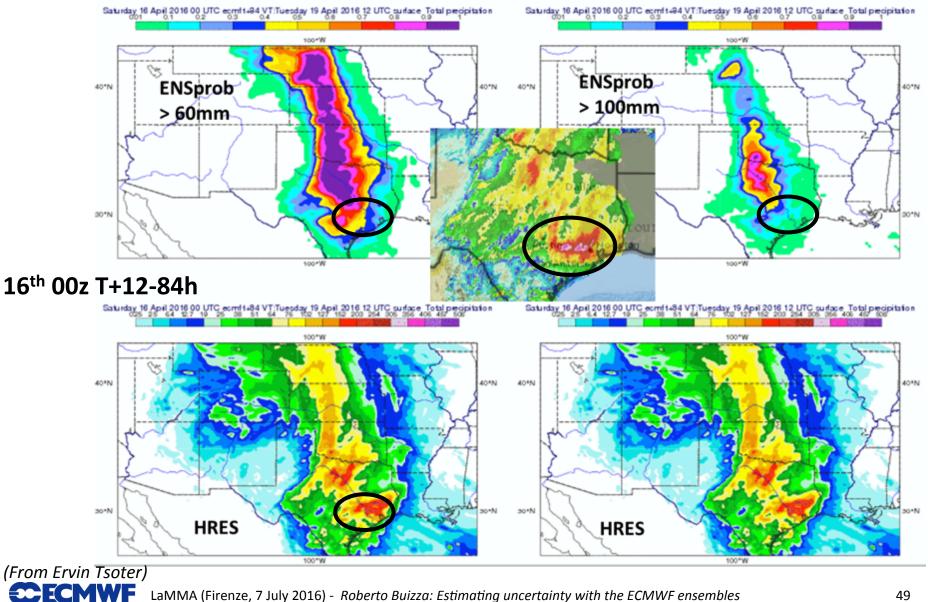




6. +3d to +1d fcs of TP between 16@12 to 19@12

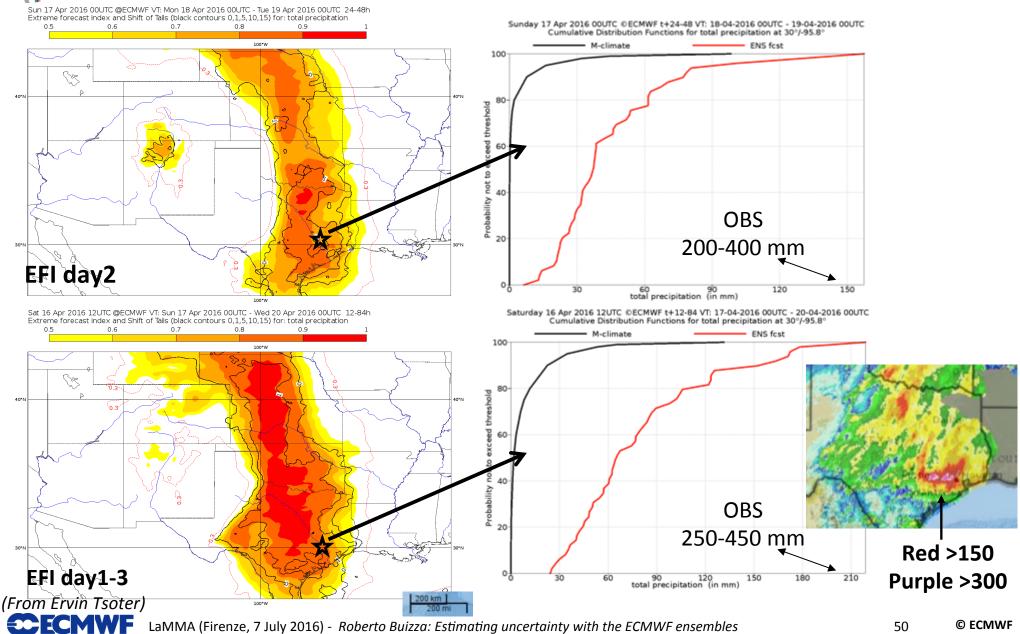


6. +3.5d fcs of TP between 16@12 to 19@12



© ECMWF

6. +2d and +3d fcs of TP between 16@12 to 19@12

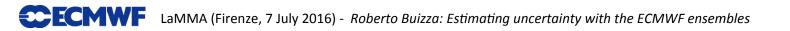




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6. Ensembles are the cornerstone of our future

Because they can be used to estimate the probability of occurrence of events of interest, to gauge how confidence we could be about a future state.



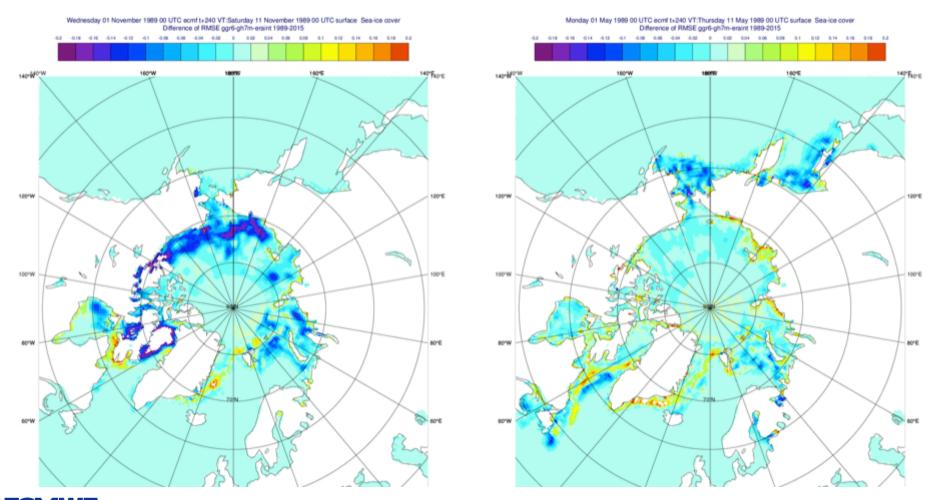
6. How can we keep improving the ensembles?

Work is progressing on many areas to further improve the ECMWF ensembles:

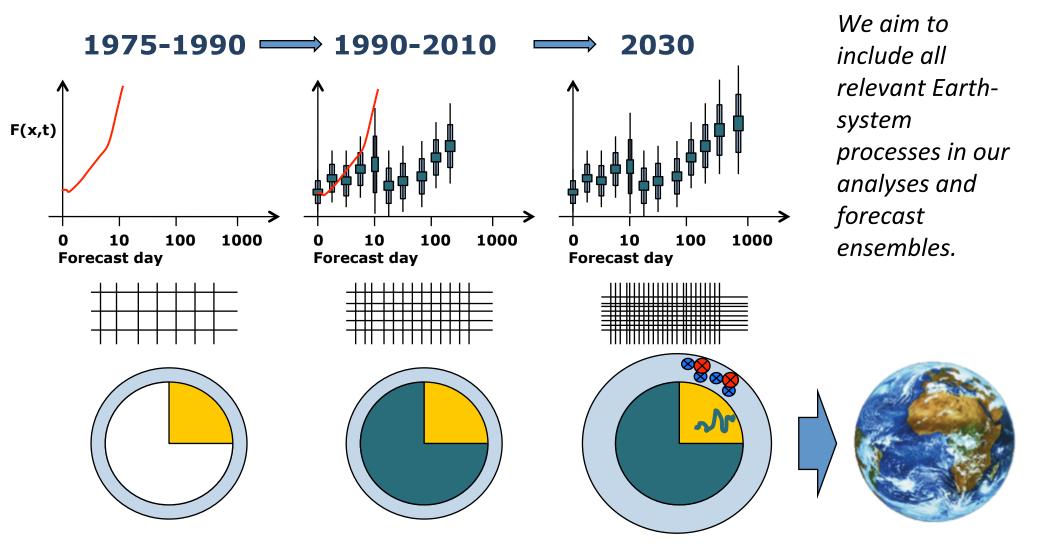
- 1. Modelling (including model uncertainty simulation): improve all model components (land, atmosphere and ocean) and increase resolution; upgrade the stochastic schemes that simulate model uncertainty
- 2. Initial Conditions estimation: integrate further the analysis and forecast ensembles (EDA/ORA and ENS) and re-assess the potential benefit of starting ENS directly from EDA analyses; assess the impact of using a more strongly coupled DA
- **3. Predictability:** identify sources of predictability, and ways to extract predictable signals for the ensemble PDF
- 4. Ensemble methods: assess whether different ensemble configurations (IC/model unc, membership, truncation, refc suite, ...) could lead to more accurate and reliable PDF fcs

6. Q4-16: ENS with higher-res ocean (0.25°-z75) & sea-ice

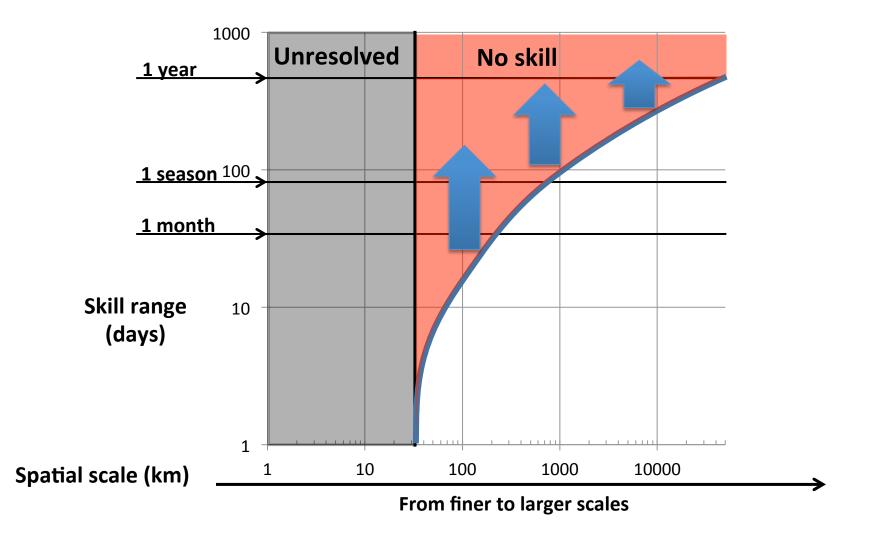
The next model cycle with include a higher-resolution ocean (0.25° degrees with 75 layers) with dynamical sea-ice in ENS, with ICs from ORAS5 ensemble of analyses.



6. 10y strategy: ensemble of Earth-system model and DA



6. So that we can further extend the fc skill horizon



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Thank you very much for your attention ...

ECMWF Annual Seminar 5-8 Sept 2016: Earth-system ...

Annual Seminar 2016

Earth system modelling for seamless prediction

5-8 September

On which processes should we focus to further improve atmospheric predictive skill?

The main themes of the 2016 ECMWF Annual Seminar are what Earth system processes are needed, and what level of complexity is required to further extend atmospheric predictive skill. These themes will be discussed taking into account the ECMWF strategy for the next 10 years, which sees Earth system modelling and assimilation as the way to improve further skill in the 1-day to 1-year forecast range covered by the ECMWF forecasts. The key questions that speakers will tackle while presenting progress and challenges in different areas of Earth system modelling are: if we want to improve the skill of weather predictions, on which of the already-simulated processes should we focus? If we introduce new processes, how much complexity is actually required?

